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Restoration of Al-Sanaf Marsh under Various Operation Conditions

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ABSTRACT

The dried Iraqi marshlands were re-flooded after the year 2003. Because of the water shortage feeds the marshes during the last years, the re-flooded marshes began to dry again. The Al-Sanaf marsh is part of the Al Hammar marsh located in the Thi Qar province. It is not separated hydraulically from the Al Hammar marsh. The study suggested separating the two marshes by replacing the culverts under security dyke with uncontrolled weir to keep the area of Al-Sanaf marsh submerged. If there is any added water, it will cross from the suggested structure to the Al Hammar marsh. A hydrodynamic and water quality routing models (RMA2 and RMA4) were prepared based on mass conservation low, mass balance model, and four scenarios were applied for the Al-Sanaf marsh based on the incoming discharges. The suggested model was calibrated with field data measured in the marsh. The four suggested scenarios are to keep the requirement of the Al-Sanaf marsh restoration. The maximum submerged area of the marsh is 100 km² under any operation conditions while this area was reduced to 72 km² under low flow conditions (minimum inflow from the feeders). The three scenarios operated considering values of inflow from Euphrates River with the required inflow from Al Khamissiya canal to keep the minimum level of salinity in the submerged area. While the fourth scenario operated with the minimum value of discharge from all feeders.

Keywords: Al-Sanaf Marsh; hydrodynamic mode, Marshland, Al Hammar Marshes, RMA2, RMA4

INTRODUCTION

The marshlands of Iraq are located in the southern part at the confluence of Euphrates and Tigris rivers. They cover an area of about 15000–20000 km²(Yasir, Rahi, & Abudi, 2018). The Mesopotamia marshlands denote the largest wetland ecosystem in the Middle East and western Eurasia (Hussain & Ali, 2006; Marghany, Hasab, Mansor, & Shariff, 2016). Three major marsh areas are considered the core of the wetlands of Iraq Al Hammar Marshes; the Central Marshes and the Al Hawizeh Marshes (Kugaprasatham, Al-Lami, & Aoki, 2014). Each major marsh zone consists of hydraulically connected shallow lakes and scattered ponds (Yasir et al., 2018).

The Tigris and Euphrates Rivers and their branches are the main source of water feeding the marshes, but the inflows to the marshes reduced on the last two decades of the past century because of the construction of major hydraulic structures and dams at the upstream zone of both rivers in Turkey and Syria (Al-Ansari, 2013; Al-Ansari & Knutsson, 2011).

In addition, the marshes were destroyed by the series of combined impact of huge drainage works carried out in the southern part of Iraq from 1980 to 1990 by the previous regime and upstream damming (Yasir et al., 2018). After 1991 and due to political reasons, the Sadaam regime started implementing five major drainage projects to prevent or reduce the water from the Tigris and Euphrates Rivers to reach the marchland area (Ali, 2013).

As a result of these scenarios, the slowdown destruction carried out by the government during the 1990s, the decreasing of wetland reached less than 15% of the natural wetland extent, which was an environmental disaster and reached about 10% by the year 2001 of the original area (Kadhim, 2005; Curtis J Richardson, 2016).

In April 2003, directly after the fall of the Saddam's regime, the dikes and earthen dams were broken by farmers and local populations releasing water return into many former marsh areas (Curtis J Richardson, 2016). As well as the Iraqi government with the assistant of other countries and international organizations started the process of restoration and rehabilitation of Iraqi marshes (Al-Ansari & Knutsson, 2011) and encourage people to return live in these area. Approximately 20% of the 15,000 km² of the former dried marshes had been re-flooded by early 2004 (Curtis J. Richardson & Hussain, 2006).

The Al Hammar marsh is one among the three marshes that constitute the formerly extensive and biodiverse Mesopotamian marshlands of southern Iraq (Al-Musawi, Al-Obaidi, & Al-Rubaie, 2018). It is located in the south direction of the Euphrates river, expanding from the west of Nasiriyah city into the borders of Basrah on Shatt Al-Arab in the east (Al-Ansari, Knutsson, & Ali, 2012). The marshland varying from 2800 km² of permanent marsh, expanding to 4500 km² during wet periods (Azhar Al-Saboonchi et al., 2011). The maximum water depth in the marsh varies from 1.8 m to 3.0 m (Foundation, 2003; Najah et al., 2009). Al Hammar marsh had been dried for over a decade, but it was reconditioned to near half its original size in the year of 2005 after a policy of restoration of marshland was initiated to recover the marshes in 2003 (Al-Gburi, Al-Tawash, & Al-Lafta, 2017). In 2002, 93% of the permanent marshes existed in 1973 had been dried and destroyed and most of people living in these area were moved to another areas. For Al Hammar marsh, not more than 14.5% of original area remained (Richardson and Hussain 2006). After 2003, excessive hard work and activities have been made to reestablish the marshes and revive the wetlands environment. These activities were succeed in 2007 for recovering almost 58% of their former area from 1972, according to UNEP/ IMOS (2007) (Mohamed & Hussain, 2012).

Furthermore, a cooperative between the United Nations Environment Program (UNEP) and United Nations Educational, Scientific and Cultural Organization (UNESCO) has been created to confirm sustainable improvement of the Marshlands in Iraqi by introducing them into the World Heritage List, as these sole wetlands represent a region of outstanding universal historical, cultural, environmental, hydrological, and socio-economic value (Al-Gburi et al., 2017; UNEP-DTIE-IETC, 2009).

In spite of the strenuous efforts from the local authorities and International Agencies to restore the marshland to the previous situation, but all of these efforts failed due to the water crisis of the water resources which supply water to the marshland.

Due to the drought conditions between 2005 and 2009, the water supplies to the marshlands were decreased, which distraught agriculture area and caused a big shortages for supplying a drinking water, mainly in rural areas. Therefore, around 39% of farming field suffered a reduction in coverage for two years in sequence between 2007 and 2009, and livestock has been decimated (Al Obaidy & Al-Khateeb, 2013). Fifty percent of the existing surface water in Iraq comes from the upstream rivers in the neighboring countries of Turkey and Iran, which directly affects the downstream rivers and the marshland in the lower zone of Iraq.

In the case of scarcity, the small amounts of water are distributed over all the area of the Al Hammar Marshes scattered on sporadic ponds not useful for different purposes. Therefore, the idea of this research is to make the part of this area of the marshes permanent, by separating the Al-Sanaf marsh from the Al Hammar Marshes and any amount of coming water will be enough to keep it as permanently immersed. If there is more water, it will cross to the Al Hammar Marshes. Thus, the existence of permanent marsh will be ensured and it will help protect the ecosystems in marsh.

This situation leads for thinking of new scenario to keep minimum area from marshland which is the main objective of this study taking Al-Sanaf marsh as a sample to study the restoration of it under various operation conditions. As a result, Authors of the current study hope that it could contribute to the management process, which not only meets the technical requirements of the World Heritage Convention, but will also introduce a new motivation to the efforts that target at protecting and preserving the environment and live conditions in the Mesopotamian Marshes.

MATERIAL AND METHODS

Description of the marsh

The Al-Sanaf marsh is located in Thi-Qar governorate between E=635237 to E=636235 and N=3401350 to N=3417030 with an area about 110 km². The boundaries of the marsh are

the Euphrates River in Suq AshShuyukh city as a north boundary, the Al Hammar marsh as an east boundary, the Main Outfall Drain (MOD) as the south boundary, and Suq AshShuyukh city as the west boundary, Figure 1 shows the general layout of the Al-Sanaf Marsh. The water from many feeders supplies the marsh; these feeders are Um Elwada and Al Kurmashia from Euphrates River and Al Khamissiya from main outfall drain, MOD. Al-Sanaf marsh was considered as a part of the Al Hammar marsh where there is no barrier between them. Over the last two decades, the earth dike with four culverts, called Security dike, was constructed between the two marshes. There are three small islands and deep waterway in the marsh. Another obstruction in the marsh is a railway with six box culverts, as shown in Figure 1 (Ministry of Water Resources & . 2006).



Fig. 1. Layout of the main feeders of AsSanna'f Marsh

Colected data

Topographical data, evapotranspiration (ETo) inside the marsh, discharge of the feeders to the marsh, and concentration of total dissolved solids (TDS) in marsh feeders, which are obtained from Center for the Restoration of Iraqi Marsh lands (CRIMW) (CRIM, 2010) as listed in Table 1. The digital elevation model (DEM), which was obtained from Shuttle Radar Topographical Mission Data of 90 meters definition. Alhamadani (Alhamdani, 2014) suggests Manning's roughness coefficients of the bed in marshland using the roughness-depth relationship which is shown in Figure 2.

Field work

The field investigation was carried out to update the collected data of the marsh with such features as topographical data, and marsh feeders. The islands, waterway, and distribution of vegetation are new features represented in the mathematical model. The topographical data is updated by surveying some locations and comparing them with the available DEM. In order to verify and calibrate the mathematical model, the discharge of the feeders and water depth within the marsh were observed. The discharges of Um Elwada, Al Kurmashia, and Al Khamissiya were measured by using a universal current meter model 6500, manufactured by Rickly Hydrological Company based on the midsection method of the U.S. Geological Survey (USGS, 1976). Figure 3 (a) shows a snapshot during the process of discharge measurement. Five points through the marsh were selected to check the water depth and TDS. The locations of these points were specified using a GPS device. Figure 3 (b) shows the locations of the points within the marsh. A scaled staff was used to measure the water depth, Figure 3 (c). The water samples were collected at a depth of 5 cm below the water surface by using a plastic bottle then the total dissolved solids were measured using a Senso Direct 150 multi meter device. Table 2 and 3 represented the measured discharges and DTS of the feeders and water depth with TDS at the tested points through the marsh.

HYDRODYNAMIC AND WATER QUALITY MODELS

This part describes the development of numerical models capable of accurately simulating the hydrodynamic behavior and water quality variation within the Al-Sanaf Marsh. Two software packages were used for the mathematical simulation purposes, namely:

• The Waterway Experiment Station, WES, RMA2 two-dimensional, finite element numerical model was used in order to determine the elevation of water surface, water depth and

		Location of feeding		Discharge, m³/s			Average	
No.	Feeder E N Ma		Max.	Min.	Average annual	annual concentration of TDS, mg/l		
1	Um Elwada	646169	3409336	29.6	3.0	13.3	2535	
2	Al-Kurmashia Canal	649135	3411477	3.9	0.4	1.8	2550	
3	Al-Khamissiya	637326	3412079	56.6	9.7	26.4	4740	

Table 1. Discharge and concentration of total dissolved solids (TDS) in marsh feeders



Fig. 2. Manning's Roughness Coefficients for Al-Sanaf marsh

velocity (magnitude and direction) throughout the marsh.

 The Waterway Experiment Station, WES, RMA4 two-dimensional, finite element numerical water quality model was used to investigate the distribution of TDS inside the marsh. The two above-mentioned models were developed by Norton, King and Orlob of Water Resources Engineers, for the Walla District Corps of Engineers, and delivered in 1973, (Donnell, 2009).

Governing Equations

The governing equations used in the mathematical model, RMA2 are the momentum and continuity equation.

The momentum equations in both x and y directions are

$$h\frac{\partial u}{\partial t} + hu\frac{\partial u}{\partial x} + hv\frac{\partial u}{\partial y} - \frac{h}{\rho} \left[Exx\frac{\partial^2 u}{\partial x^2} + Exy\frac{\partial^2 u}{\partial y^2} \right] + gh\left(\frac{\partial a}{\partial x} + \frac{\partial h}{\partial x}\right) + \frac{gun^2}{\left(1.486h^{1/6}\right)^2} (u^2 + v^2)^{0.5} - (1)$$

 $-2h\omega vsin \phi = 0$

And

$$h\frac{\partial v}{\partial t} + hu\frac{\partial v}{\partial x} + hv\frac{\partial v}{\partial y} - \frac{h}{\rho} \left[Eyx\frac{\partial^2 v}{\partial x^2} + Exy\frac{\partial^2 v}{\partial y^2} \right] + gh\left(\frac{\partial a}{\partial y} + \frac{\partial h}{\partial y}\right) + \frac{gvn^2}{\left(1.486h^{1/6}\right)^2} (u^2 + v^2)^{0.5} -$$
(2)

 $-2hv\omega vsin \emptyset = 0$

The continuity equation in unsteady flow problems is:

$$\frac{\partial h}{\partial t} + h\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y}\right) + u\frac{\partial h}{\partial x} + v\frac{\partial h}{\partial y} = 0 \qquad (3)$$

While the governing equation that used in the mathematical model, RMA4 is the depth-averaged transport and mixing equation:

$$h\left[\frac{\partial c}{\partial t} + u\frac{\partial c}{\partial x} + v\frac{\partial c}{\partial y} - \frac{\partial}{\partial y} - \frac{\partial}{\partial x}\right]$$

$$D_{x}\frac{\partial c}{\partial x} - \frac{\partial}{\partial y}D_{y}\frac{\partial c}{\partial y_{c}} + \frac{R(c)}{h}\right] = 0$$
(4)

Where h is represent water depth; u and v, are referring to velocities in Cartesian coordinates;



Fig. 3. Field work (a- flow measurement, b- point location, c- water depth measurement

t, time; ρ , density of fluid; Exx, eddy viscosity coefficient on x axis surface; Eyy, eddy viscosity coefficient on y axis surface; Exy and Eyx, shear direction on each surface; g, acceleration due to gravity; a, elevation of bottom; n, manning's roughness; ω , rate of earth angular rotation; ϕ , local latitude; c, concentration of pollutant for a given constituent; Dx and Dy, turbulent mixing, dispersion, coefficients; Kc, first order decay of pollutant; R(c), rainfall/evaporation rate and σ , source/sink of constituent.

The continuity and momentum equations solved the equations by using the finite element technique, using the Galerkin method of weighted residuals. The quadratic and linear shape functions were used for interpolation of flow velocities and water depths. Fully implicit solution and the set of simultaneous equations were solved by Newton-Raphson nonlinear iteration. As with the continuity and momentum equations, the equation of transport and mixing solved with the finite element method using Galerkin weighted residuals. The transport model handles one-dimensional segments, two-dimensional quadrilateral or triangles curved lament edges. Spatial integration of the equations is performed by Gaussian techniques, (Donnell, 2009).

Model Parameters

The parameters of RMA2 and RMA4 models are the hydraulic characteristics of the water bodies that are represented in the equations of motion and transport and mixing process. These

 Table 2. The measured discharges and TDS of the feeders

Feeder	Measured discharge, m ³ /s	Concentration of TDS, mg/l		
Um Elwada	10.7	2650		
Al-Kurmashia Canal	2.1	2800		
Al-Khamissiya	18.7	5200		

parameters cannot be estimated directly in the field, but can be identified after developing the finite element mesh and specifying the boundary conditions depending on previous studies, then checked after the calibration process. Some of these parameters include Manning's roughness (n), turbulent exchange coefficients, and eddy viscosity. The effects of wind, decay of pollutant and source of constituent were not considered.

Boundary Conditions

There are several boundary conditions from which can be specified at each node in the hydrodynamic model. These conditions including: Parallel flow boundary condition, flow boundary condition, water level boundary condition, stagnation point boundary condition, reflection/ absorption boundary condition, wind field boundary condition and wave field boundary. The water level boundary condition is typically assigned along the downstream boundary nodes of the network while boundary nodes along the upstream end of the network are typically assigned an exact flow boundary condition. The concentration of the pollution can be specified as a boundary condition for water quality model when the water is entering the model.

Hydrological Analysis

Depending on the principle of mass conservation law, the hydrological routing to Al-Sanaf marsh, the discharges of feeders that incoming from Euphrates River and Al Khamissiya were computed to maintain the constant submerged area of the marsh. This amount of inflow water must be equal to the evapotranspiration, ETo from the marsh add to the minimum monthly outflow requirements to flushing the accumulated salts in the marsh. This hydrological routing was established in four scenarios, three scenarios by taking the minimum, average and maximum annual

Table 3. The measured water depth and TDS at the tested points through the marsh

Deint	Loca	ation	Maggured water depth m	Concentration of TDS, mg/l	
Point	E	N	ivieasured water deptri, m		
1	638050	3413947	0.40	5850	
2	641967	3410030	0.43	5100	
3	646797	3408849	0.88	3020	
4	649547	3404526	1.17	5200	
5	651575	3409470	1.61	3510	

discharge of the feeders from Euphrates River with calculated discharge from Al Khamissiya canal (salty water) to maintain the submerged area. Under these scenarios, the minimum monthly discharge of outflow is 5 m³/s and submerged area equals 100 km². The forth scenario is made by taking the minimum inflow from both Euphrates River and Al Khamissiya canal with no outflow in Jun to maintain the submerged area of 72 km².

RESULTS AND DISCUSSION

Data analysis

The topography of the Al-Sanaf marsh was developed based on the available digital elevation model (DEM), which was obtained from Shuttle Radar Topographical Mission Data of 90 meters definition, shown in Figure 4. it was updated according to the obtained data from CRIMW and Alhamdani (Alhamdani, 2014; CRIM, 2010).

Since the Al-Sanaf marsh is a part of the Al Hammar marsh, the data of evapotranspiration and precipitation can be applicable. Figure 5 (a) shows the monthly mean evapotranspiration within the marsh based on the data obtained. From this figure, it can be noted that the maximum value of evapotranspiration is 458 mm during June. General Iraqi Meteorological Authority and Seismology provided the precipitation within the study area as shown in Figure 5(b). As shown in the figure, the annual amount of the precipitation is less than 100 mm, which means the area can be categorized as dry.

Area and Storage Elevation Curves

The elevation-storage curve is one of the most significant physical properties of any reservoir.

Depending on the updating DEM of the Al-Sanaf marsh, the area elevation curve was obtained, as shown in Figure 6 the relation of the curve is non-linear.

Calibration of mathematical models

Calibration refers to the adjustment in values of the parameters that have lack of certainty. As part of the calibration process under the same conditions, the model input parameters were adjusted to obtain a close match between the simulated and observed/measured data (Novikov & Bagtzoglou, 2006). The calibration process involved 8 iterations; each one has an adjusted value of Peclet Number. The selected values of Peclet Number to be used in next model runs are those that give minimum error between the measured values and that by the models. The measured water depths were used in the calibrating process in RMA2 model runs. The minimum value of error between the measured water depths and results of the model runs were obtained with the Peclet Number of 23. Figure 7 (a) shows measured water depths versus the RMA2 model results. The slight difference between the measured and calculated water depth is because of the inaccurate marsh topography at some points.

The set of concentration of TDS data that was measured was used to calibrate the value the Peclet Number in the RMA4 model runs. The minimum error between the measured data and results of the model runs were obtained with a Peclet Number of 20. Six iterations were made to reach this value. Figure 7 (b) shows the concentration of TDS of field measurements versus that of the RMA4 model results, when using the calibrated values of Peclet Number in the runs of the RAM4 model. The maximum percentage of error was 12% at point 3 because of this point is quickly affected by the Um Elwada feeder.



Fig. 4. The topography of Al-Sanaf after CRIMW and Alhamdani (Alhamdani, 2014; CRIM, 2010)



Fig. 5. Evapotranspiration and precipitation of Alsenaf marsh

(a - Evapotranspiration and b- Rainfall)



Fig. 6. Curve of the area elevation for Al-Sanaf marsh

Results of hydrodynamic model

Depending on the hydrological analysis and boundary conditions, the hydrodynamic mathematical model were carried out including the mesh generation, defining the model parameters, calibration processes, and the run results under different operation scenarios. Table 4 shows the results of the hydrodynamic mathematical model under the conditions of four scenarios. The simple deference between the values of outflow in the hydrological analysis and mathematical model occurred because of the deference in the submerged area that was calculated with two methods. Figure 8 shows the distribution of water depth and velocity pattern for all scenarios. The results show that the water depth within the marsh affected by the water surface elevation at the outlet, discharge of the feeders and topography of the marsh. The magnitude and direction of the velocity through the marsh depend on the location and the features of the marsh such as islands, borders and deep waterway. In addition,

the velocity magnitude increased at the culverts under railway.

The calculations of the forth scenarios are listed in Table 5 as a sample. Table 6 listed the scenarios of hydrological analysis. The values of the inflow discharges for each scenario were considered as upstream boundary conditions for the hydrodynamic model, while the downstream boundary condition is considered as constant water level at the outlets of the marsh. This elevation for each scenario obtained from area-elevation curve presented in Figure 5 depended up on the selected submerged area. All these scenarios were tested with mathematical models with two locations of outlet for each scenario.

Results of water quality model

The results of computing the TDS distribution patterns within the Al-Sanaf marsh using the RMA4 model were shown in Figure 9. It can be noted that the distribution of TDS was affected by the discharge and concentration of TDS of the



Fig. 7. Calibration of mathematical models (a- Water depth and b- TDS values)

feeders and evapotranspiration. Because of the high concentration of TDS in the Al Khamissiya feeder that feed the marsh from MOD, the marsh was mainly affected by it. The results showed that the concentrations of TDS at the marsh outlet were 6980, 5350, 3580 and 8150 mg/l for four scenarios, respectively. Additionally, it can be noted that the maximum concentration of TDS at the fourth scenario when the percentage of the discharge of Al Khamissiya canal to another feeders is maximum. The concentrations of TDS at the outlet depending on the principle of mass balance were 7325, 5502, 3509 and 8505 mg/l for four scenarios, respectively. From the distribution of concentration of TDS, it can be noted that the water quality deteriorated at the stagnation region where evapotranspiration was high.

CONCLUSIONS

The deterioration of the Mesopotamian marshlands during the last two decades is an example of the negative impact of human activities on marshlands. Restoring all marshlands will require many years and an array of people and technology. According to the current condition of the feeders and their feeding points into the Al Hammar marsh, they are not suited for restoration in the entire area. Al-Sanaf is part of the Al Hammar marsh; there is no any structure separate between the two marshes. In order to ensure that the marsh is submerged, it must be separated from the Al Hammar marsh by closing the culverts under the security dyke and replaced with uncontrolled weir. The maximum submerged area of the marsh is 100 km² under any operation conditions while this area reduced to 72 km² under low flow conditions (minimum inflow from the feeders). The minimum crest level of the weir must not be lower than 2.8 m.a.s.l in order to keep the submerged area within 100 km². In order to keep the requirement of Al-Sanaf marsh restoration, four scenarios were suggested, in which any added water will go to the Al Hammar marsh. The minimum deteriorated area with high concentration of TDS when the discharge from the Al Khamissiya canal is kept to minimum. If the discharge from the feeders that feed the marsh from Euphrates River is greater than 24 m³/s, there is no need to feed the marsh from Al Khamissiya canal. This discharge covered the evapotranspiration and

Table 4. The results of the hydrodynamic mathematical model of four scenarios

Scenarios	Submerged area km ²	Inflow m ³ /s	Evapotranspiration	Outflow	Water surface elevation at outlet, m.a.m.s.l
			m³/s	m³/s	,
1	100	23.4	9.28	14.3	2.8
2	100	23.35	9.28	14.25	2.8
3	100	33.5	9.28	24.4	2.8
4	72	13.1	6.68	6.53	2.4

minimum requirements of outflow to flush the salty water. The minimum concentration of TDS

at outlet is 3580 mg/l when the discharge from Euphrates River is at maximum value.



Fig. 8. Water depth and velocity pattern distribution of suggested scenarios in Al-Sanaf marsh

Month	Eto, mm	Eto, m³/s	feeders Discharge m³/s	Discharge of Al Khamissiya Canal, m³/s,	The outlet Discharge m ³ /s
Jan.	50	1.34	3.40	9.70	11.76
Feb.	75	2.23	3.40	9.70	10.87
Mar.	130	3.49	3.40	9.70	9.61
April	200	5.56	3.40	9.70	7.54
May	350	9.41	3.40	9.70	3.69
Jun	475	13.19	3.40	9.70	0.0
July	450	12.10	3.40	9.70	1.00
Aug.	410	11.02	3.40	9.70	2.08
Sept.	350	9.72	3.40	9.70	3.38
Oct.	250	6.72	3.40	9.70	6.38
Nov.	120	3.33	3.40	9.70	9.77
Dec.	75	2.02	3.40	9.70	11.08
Averages		6.68	3.40	9.70	6.42

Table 5. The required inflow and outflow to maintain the area of 72km².

Table 6. The scenarios of hydrological analysis

Scenarios	Submerged area km ²	Discharge from the Euphrates River, m ³ /s	Average annual discharge from Al Khamissiya canal, m3/s	Average annual Eto, m³/s	Average annual outflow m³/s
1	100	3.4	20	9.28	14.12
2	100	15.1	8.25	9.28	14.07
3	100	33.5	0.0	9.28	24.22
4	72	3.4	9.7	6.68	6.42



Fig. 9. The results of computing the TDS distribution patterns within Al Sanaf marsh using the RMA4 model Scenario 1, b- Scenario 2, c- Scenario 3 and d- Scenario 4)

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